



## Review of seawater natural organic matter fouling and reverse osmosis transport modeling for seawater reverse osmosis desalination

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### ABSTRACT

To date, over 80 papers on transport modeling and natural organic matter (NOM) relating to seawater reverse osmosis (SWRO), have been reviewed. As a result of such focus, NOM, one of the main foulants related to reverse osmosis (RO) membranes, has been shown to possess intrinsic chemical complexities and ambiguities, necessitating further investigation. Consequently, since such NOM fouling and transport mechanisms associated with SWRO are not fully understood, a summation of previous studies has been included in the paper in question to systematize information, not only as to RO membrane transport modeling, but NOM fouling characteristics, as well. Accordingly, RO transport models in the review are classified into three categories: diffusion-based, pore, and irreversible thermodynamic models. In addition, specific features, unique assumptions, and applications for each model are examined. The paper consists of the following components towards meaningful understanding of NOM fouling model development during SWRO: 1) SWRO fundamentals as to membranes, 2) NOM fundamentals as to seawater, 3) RO transport modeling theories, 4) conclusion, and 5) future directions of NOM fouling model development.

*Keywords:* Natural organic matter (NOM); Seawater reverse osmosis (SWRO); Membrane transport models; Fouling mechanism

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### 1. Introduction

Desalination processes have emerged as an effective solution for solving potable water shortages, quickly emerging as a major global problem [1,2]. Especially, seawater reverse osmosis (SWRO) membrane desalination, in relation to thermal desalination, e.g., multistage flash desalination (MSF) and multi-effect distillation (MED), is more technologically feasible in reducing energy consumption during fresh water conversion [3]. Apart from such merits, membrane fouling during SWRO applica-

tion persists as a major impediment, reducing operation efficiency during filtration process.

Reverse osmosis (RO) membrane fouling is classified according to the following foulant types: particle/colloidal, biological, inorganic (scaling), and organic fouling [4]. Particularly, natural organic matter (NOM) fouling has emerged as a focal point in research and application, playing a key role in irreversible fouling generation during SWRO desalination. Contrary to reversible fouling, easily cleaned by back washing, irreversible fouling requires chemical cleaning due to permanent bonding of organic matter and other foulants (e.g., inorganic matter and colloids) [4,5]. However, fundamental NOM fouling mecha-

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nisms have not been fully understood due to possessing a complex mix of particulate and soluble components, both inorganic and organic matters, distinguishing such mechanisms from a variety of other sources [6].

Most previous studies dealing with SWRO desalination models have avoided focusing on NOM fouling, rather centering on general mass transport modeling. Moreover, a variety of theoretical RO transport models have tended to be directed towards underlying membrane separation mechanisms as well as membrane property influences, combined with operational effects relating to salt rejection [7–9]. Generally, such models were developed under general aspect; however, the inclusion of specific RO transport models dealing with NOM fouling was overlooked, failing to prevent and reduce serious fouling during SWRO application. Conversely, the paper in question is focused not only on fundamental aspects of RO application and NOM via corresponding fouling mechanisms, but on RO transport model theories, as well. Furthermore, future directions and approaches in developing reasonable NOM fouling and SWRO models are addressed in the final section.

## 2. Fundamentals of seawater reverse osmosis desalination

### 2.1. Seawater

Common seawater consists of 96% water, the remaining 4% of the total dissolved solids (TDS). Seawater TDS mainly consist of inorganic ion compositions, approximately 0.002–0.004% of TDS representing organic matter [10,11]. In general, average seawater salinity represents about 35% of the total weight [12] ranging from 32 to 40% of total weight in the open sea [13]. Ocean salinity varies according to freshwater input (e.g., precipitation and river/groundwater runoff), seawater evaporation rate, and seawater temperature [13]. Table 1 demonstrates the effects of temperature on salinity, revealing higher TDS during exposure to higher temperatures due to increased seawater constituent solubility [12].

Chloride and sodium ions are considered major seawater components, overall seawater composition being

Table 1  
Salinity and temperature of various seawater sources [12]

Seawater source	TDS (mg/L)	Avg. temperature (°C)
Pacific/Atlantic Ocean	33,500	18
Caribbean	36,000	26
Mediterranean	38,000	26
Gulf of Oman, Indian Ocean	40,000	30
Red Sea	41,000	28
Arabian Gulf	45,000	26

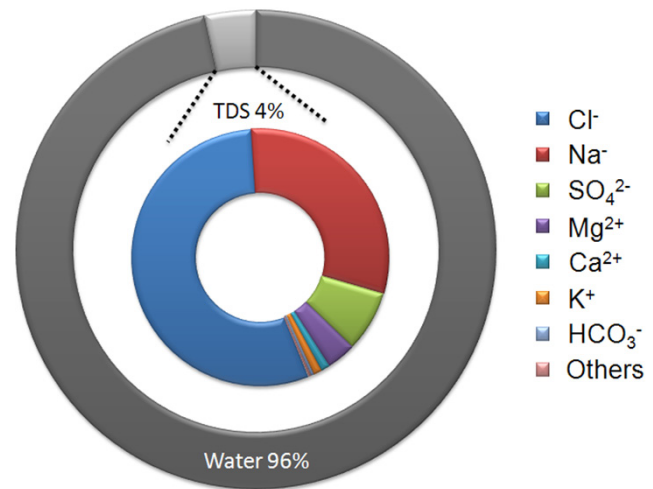


Fig. 1. Concentration of major seawater ions (ppt by weight), adapted from [9].

demonstrated in Fig. 1 [12]. Accordingly, widespread problems during SWRO application result in high energy input and the necessity of clean-up application. Specifically, scaling from inorganic materials and complex fouling from organic matters mixes with microorganisms. Such difficulties have profound effects during reverse osmosis application, i.e., decreased performance and productivity, as well as increased production costs [14,15].

### 2.2. Seawater reverse osmosis process

Desalination is a purification process, converting common seawater into pure potable water. Generally, three groups of desalination technology exists: MSF, electrodialysis, and RO process. Among such technologies, RO process represents the most popular and widely used technique due to lower energy consumption [10]. Further, the RO process offers promising treatment for seawater desalination, including high water pressure application across membranes, as well as forced feeding through opposite membrane sites [10]. Since such membranes possess a unique property, i.e. semi-permeability [10], which possible permeates for water not sea salts [16]. Standard pressure during seawater desalination commonly requires a high range of 55–68 bar [17]. Factors affecting process performance, such as feed water composition and membrane properties, are usually selected as parameters towards maximizing process effectiveness. However, membrane surface properties have represented the primary focus in previous studies due to ease of control [18]. Initially, membrane material development commenced with the use of ceramic membranes discovered by Pfeffer and colleagues in the 1850s [16]. Afterwards, Reid and Breton developed the use of cellulose acetate films in 1959 [19]. Such films measured 5–20 μm in thickness, resulting in very low permeate fluxes. However, by

applying high pressure on the feed solution, up to 69 bar, the membranes were capable of eliminating over 98% of existing salt. Recently, cellulose acetate membranes, developed by Loeb–Sourirajan, have been able to operate 10 times faster than Reid and Breton's membrane, while maintaining the same rejection rate performance. Such innovation hastens effective development of RO technology [16].

SWRO application includes the following processes: seawater intake, pre-treatment, RO membrane, and post-treatment [4,20]. SWRO application commences during feed water containment from the sea via coast and beach wells, or open seawater intake systems [21]. Subsequently, intake water condition is further adjusted as to pH value, afterward being exposed to pre-treatment in order to separate particulate matter. At the end of the pre-treatment process, antifoulants are added to prevent fouling. Afterwards, treated water is pumped to RO membranes by means of high water pressure. Finally, pure water is re-mineralized, re-hardened, disinfected by chlorination, finally meeting drinking water standards [10]. Fig. 2 demonstrates the schematics of general SWRO application.

### 2.3. RO membrane performance determination

SWRO performance is influenced by the correlation of several factors including feed water quality, operating conditions, membrane characteristics, concentration polarization, as well as foulant characteristics and fouling mechanisms [22,23]. The major governing factors determining RO performance include membrane properties (i.e. membrane material chemistry and physical structure) and fouling development. Membrane surface properties are directly affected filtration efficiency. However, supplementary parameters, including membrane pore dimension, barrier layer thickness, and elemental composition, are ideally considered in order to provide accurate,

precise, and effective evaluation [24,25]. Additionally, permeate flux and solute rejection rates, due to simplicity and speed of onsite measurement, are key factors in determining efficacy. In order to maximize efficiency, developing membranes with specific goals of high foulant resistance, high performance, as well as longevity are vital [23]. Furthermore, a clear understanding of fouling mechanisms, in unison with effective fouling protection or reduction options, ideally advances application.

### 2.4. Seawater RO fouling

Scaling and fouling are often singled out as phenomena inflicting potentially serious harm during SWRO application. The potential of such harm as to RO membrane fouling is largely dependent upon feed water composition, associated with the accumulation of rejected salts on membrane surface during filtration [10]. Seawater foulants are classified into four categories: inorganic, colloidal, biological, and organic foulants [4]; cause-effects of seawater foulants shown in Table 2. Among all foulants, NOM is capable of generating significant fouling. Since NOM represents a complex mixture of inorganic and organic origins, changing according to environmental conditions (e.g., pH), precise operative mechanisms are largely undiscovered and poorly understood [26].

### 2.5. RO fouling mechanisms

Generally, RO membranes are assumed to represent non-porous membranes; therefore, adhesion among foulant molecules, as well as between foulants and membrane surfaces, account for dominant fouling mechanisms [28,29]. The sequence of RO membrane fouling initially includes foulant deposition on membrane surfaces due to adhesion forces between foulants and membrane surfaces. Afterwards, critical fouling layers are developed. Subsequently, intermolecular adhesion among bulk and

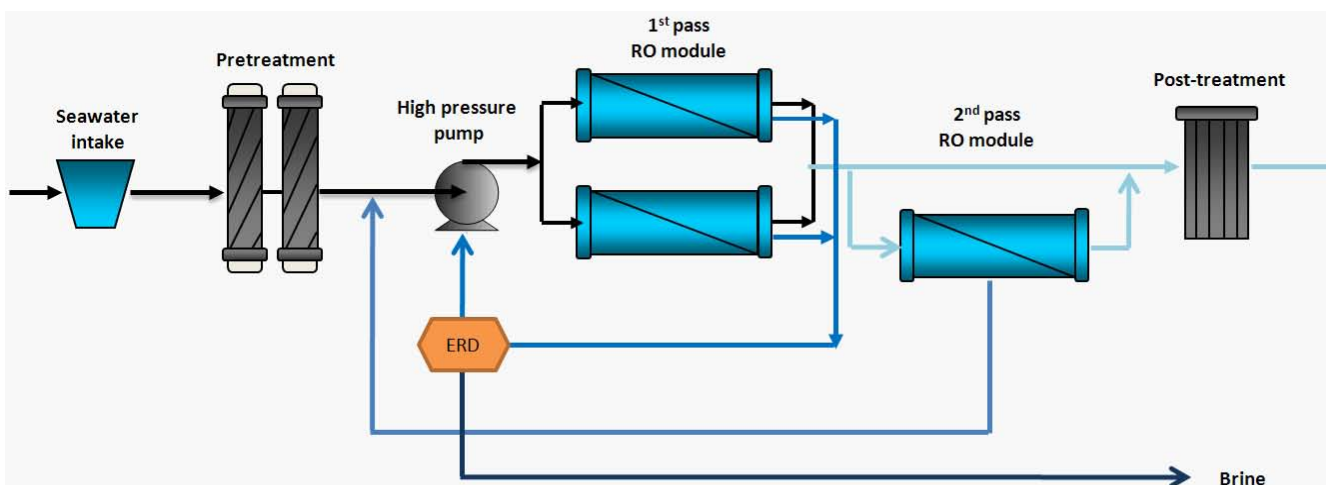


Fig. 2. Schematics of general SWRO processes.

Table 2  
Cause–effects of seawater foulants [27]

Foulant	Mechanism	Cause	Effect
Colloidal	Deposition	Accumulation of particles and macromolecules on, in, and near membranes	Creation of additional resistance layers as to permeation
Organic matter (e.g., polyphenolic compounds, proteins, and polysaccharides)	Adsorption	Permeate resistant layer formation via negatively charged functional groups on organic foulants with charged membrane surface affinity	Increased cohesion as to membrane surfaces
		Interaction between organics and microorganisms	Biofilm formation promotion
Inorganic (e.g., iron, silica, aluminum, calcium, phosphorus, and sulfate)	Deposition	Promotion of inorganic matter deposition as to concentration polarization	Salt precipitation and suspension on membrane surfaces, leading to scaling and fouling
Biofouling (e.g., bacteria, algae, and fungi)	Adhesion	Microorganism adhesion and biofilm growth on membrane surfaces	Bacteria enzymatic biodegradation of membrane material reducing membrane longevity

membrane surface-deposited foulants is established on governing mechanisms [28]; in this case, diffusion which represents apparent foulant transport. Conversely, in regards to the molecular facet, RO membrane is assumed as being microporous as well. In such cases, foulant transport not only takes place by means of membrane surface diffusion, but also by convection transport through microporous [27]. For organic fouling, the interaction between foulant-membrane as well as foulant-foulant surfaces is promoted by hydrogen bonding [30]. Additionally, other studies have demonstrated that various organic solutes interact with RO membranes by means of absorption mechanisms [31–33].

### 3. Fundamentals of NOM in seawater

#### 3.1. Seawater natural organic matter

Although organic matter concentration within seawater is insignificant compared to inorganic constituents, such substances are more acutely problematic during reverse osmosis desalination [10]. Organic matter, by merging with inorganic particles as well as microorganisms, advances the occurrence of irreversible fouling. Consequently, application of higher water pressure as to normal operation, is required to maintain the same rate of permeate flux, necessitating chemical cleaning as well.

Over 60–80% of organic matter dissolved from saltwater is represented by humic substances [26,34]. Humic substances comprise a general class of ubiquitous material found within terrestrial and aquatic environments, further affecting the aesthetic quality of water by imparting a general brown hue [10]. Humic acids are generally

thought to substantially harm RO application due to recurrent gel formation, akin to fouling layering, by means of organic compound and multivalent ion integration [10]. The adsorption of such complex organic matters on membrane surfaces results in rapid permeability decline. Moreover, NOM is possibly broken down into smaller fragments during feed water chlorination, thereby losing inherent inert properties and becoming primary nutrient sources for bacteria. Accordingly, interaction between fragmented organic matter and microorganisms gives rise to critical biofouling. Additionally, such minute NOM particles are transformed into carcinogenic organic compounds being toxic to humans. As a result of such by-products, RO plant operators are obliged to increase operation cost during post-treatment before water is finally distributed [10].

#### 3.2. Chemistry of NOM

NOM chemistry within seawater demonstrates a wide range of molecular weights and functional groups. Such substances are formed by combination of allochthonous as well as autochthonous input. In general, humic substances are differentiated as to hydrophobic and hydrophilic fractions. Hydrophobic NOM fractions, vis-a-vis hydrophilic fractions, are more likely to be absorbed on membrane surfaces. In addition, previous studies have demonstrated that NOM adsorption mechanisms on membrane surfaces increase proportionally as to molecular weight [35,36]. Moreover, divalent ions with high molecular weight NOM, compared to low molecular weight, have been promoted as being more effective in regards to fouling [37].



3.3. Factors affecting NOM fouling

NOM fouling is likely affected by several factors including NOM characteristics (e.g., hydrophobic or hydrophilic), solution chemistry (e.g., pH, temperature and ionic strength), membrane characteristics (e.g., surface charge and morphology) and operating conditions (e.g., permeate flux and velocity) [35]. A diagram of the factors affecting NOM fouling is demonstrated in Fig. 3. Moreover, previous studies have revealed the effects of fouling factors as to seawater NOM fouling, as shown in Table 3.

3.3.1. Physical operating conditions

Operating conditions include permeate flux [4,46–48], pressure [49], and mass transfer properties of fluid boundary layers are considered as factors affecting NOM transport on membrane surface. Further, such operating conditions affect not only fouling efficacy, but characteristics, as well. Accordingly, NOM fouling is controlled by the optimization of such operating conditions.

3.3.2. Solution chemistry

Factors involved in feed solution chemistry, such as ionic strength [47], pH [46,49–52], as well as monovalent and divalent ion concentration [46,50,51,53] represent major factors in NOM absorption acceleration on membrane surfaces. Furthermore, such factors help to introduce electrostatic interaction not only among solutes and membrane surfaces, but exclusively among solutes, as well. In brief, various fouling characteristics are generated by means of solution chemistry diversity.

3.3.3. Membrane properties

Membrane properties also influence fouling potential. Properties such as surface characteristics (e.g., surface roughness, charge, and hydrophobicity) [18], surface structures and surface chemical properties [38,45–47,49,50,] are representative. Accordingly, beneficial characteristics during membrane producing are the following: increased smoothness, increased negative charge, and hydrophobic membrane reduction [18].

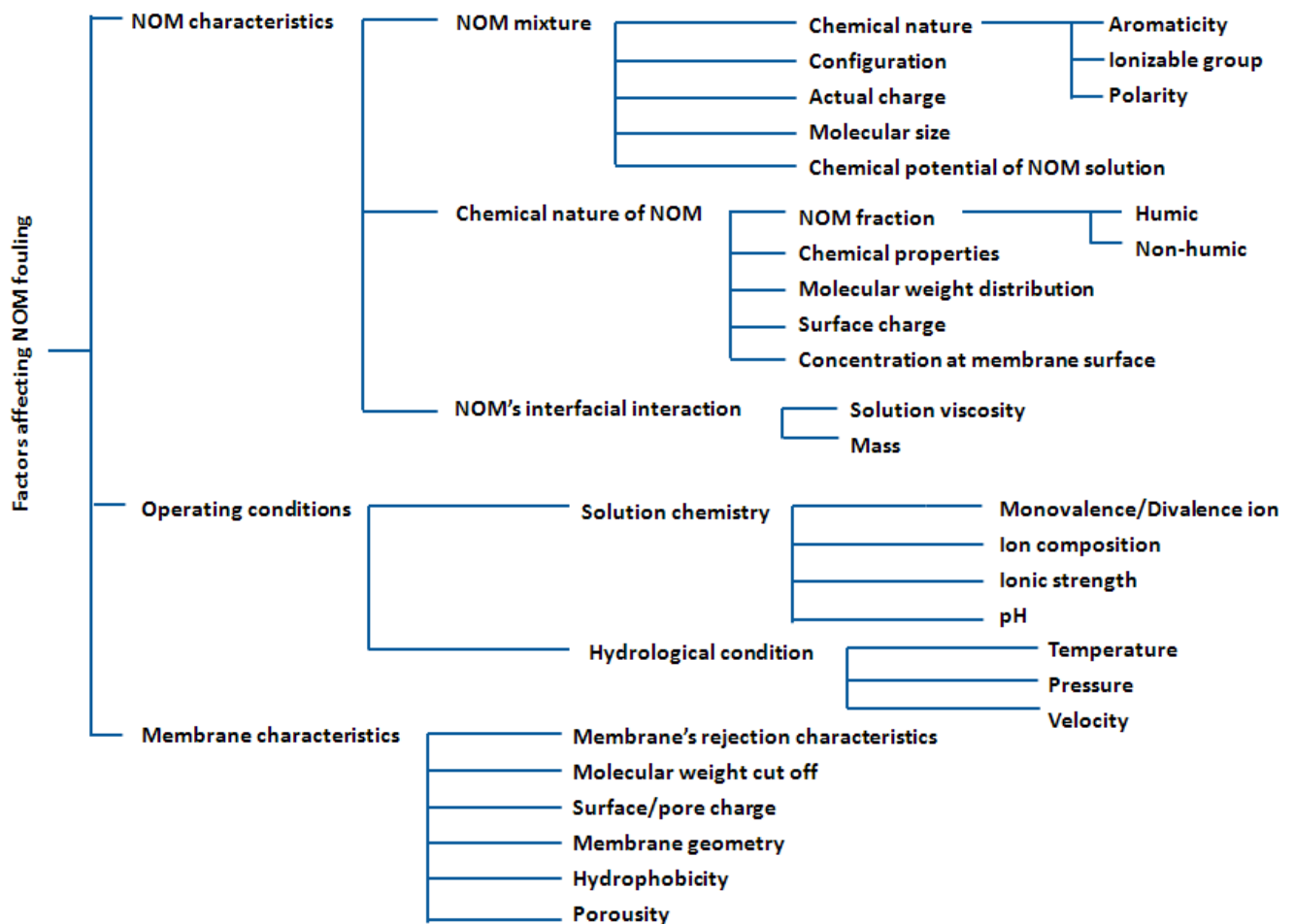


Fig. 3. Diagram of factors affecting NOM fouling.

Table 3  
Effects of fouling factors as to seawater NOM fouling

Factor	Parameter	Cause-effect	References
Feed chemistry	Ionic strength	The effects of electrostatic and hydrophobic forces as to fouling shape and characteristics (e.g., dense thick or loose sparse thin fouling layers) impacting permeate production	[38]
	pH	The effects of electrostatic forces on fouling shape and characteristics (e.g., dense thick or loose sparse thin fouling layers) impacting permeate production	[38]
	Pressure	The effects of pressure strength as to fouling layer compaction	[38]
Membrane properties	Roughness	The production of low interaction energy wells due to rougher surfaces resulting in preferential colloidal particle deposits	[39–41]
	Charge	Electrostatic repulsion between evenly charged foulants and membrane surfaces allowing foulant adhesion	[42–44]
	Hydrophobic	More severe impairment of hydrophobic membranes due to membrane fouling as to hydrophilic membrane impairment due to strong hydrophobic interaction, possibly allowing multi-fouling layering on membrane surfaces	[42,50]

4. Theoretical RO membrane transport models

According to existing models, RO transport models are classified into 3 categories based on membrane surface structures (i.e., non-porous, porous, and irreversible thermodynamic-based models) [7]. Since transport mechanisms within membranes are governed by both solvent and solute transports (e.g., diffusion and convection) [54,55] such mechanisms, as well as membrane characteristics and structures, represent vital factors in

developing and applying NOM fouling models. For clarification, Fig. 4 demonstrates existing RO transport models. In lieu of ambiguous NOM fouling mechanisms employed during SWRO, e.g., being less developed and effectual than other foulants, further study is required. Likewise, complex and vague NOM properties, as well as minimal concentration within seawater, represent additional sources of concern. Moreover, several unknown fractions and functional groups need to be characterized and identified in order to insure future progress. There-

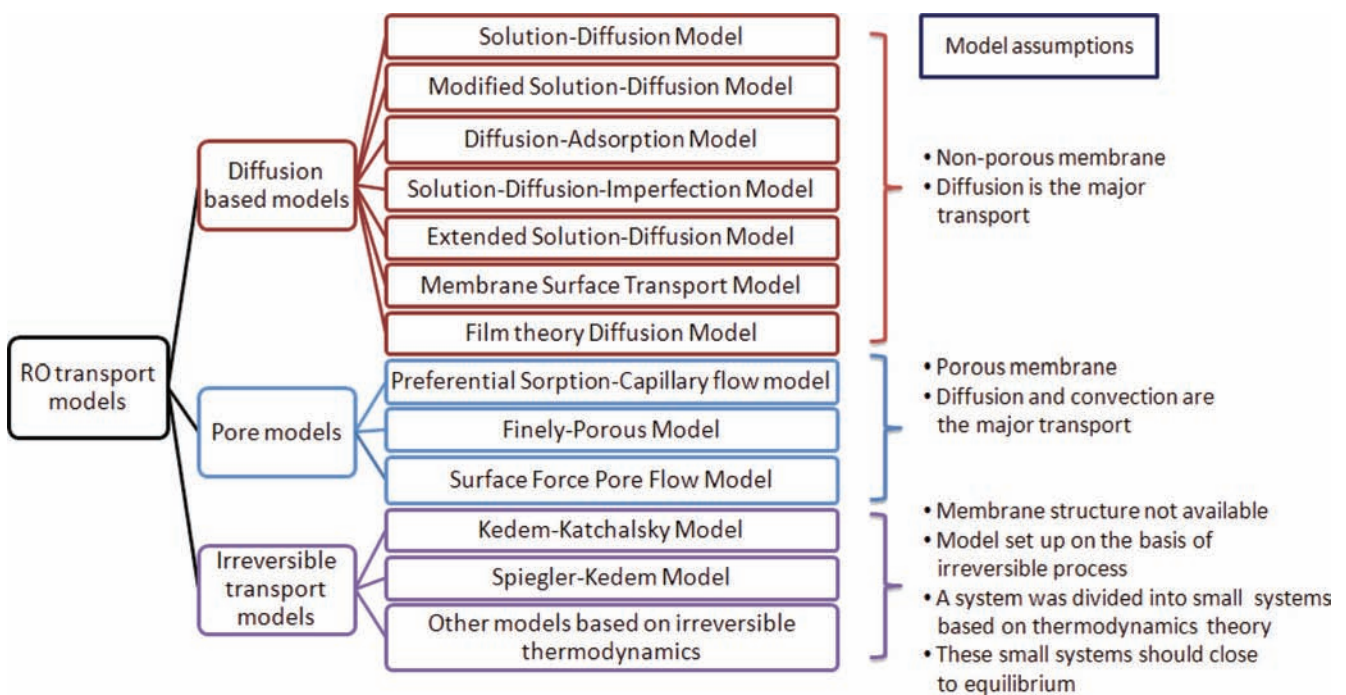


Fig. 4. Diagram of existing RO transport models.

fore, specific models for NOM fouling during SWRO have not been completely developed yet. A number of earlier studies are directed at attempting to modify and apply such models towards NOM fouling prediction, however the majority of the studies reveal that such models fail to predict effectively due to diluted NOM concentration.

#### 4.1. Non-porous models (diffusion-based models)

Diffusion-based models operate under the assumption that RO membranes are non-porous, thus NOM transports, as well as other particles, subsist among interstitial spaces of polymer chains or nodules. Hence, the incidence of diffusion represents evidence of transport, consequently supporting such an assumption. Accordingly, solute flux depends on transmembrane pressure and respective concentration variation across membranes, also known as the molecular chemical potential gradient [29].

##### 4.1.1. Solution–diffusion model

The following simple and popular model is typically applied in order to predict solvent and solute transport during RO when membrane surfaces are assumed to be completely non-porous [27]. Thus, in such a case, only diffusion accounts for transport. As to application, previous studies have applied models in accordance with concentration polarization theory, simulation results revealing robust agreement with experimental results over a range of operating conditions [56]. The governing equations contain the following two crucial coefficients: solvent permeability and solute permeability coefficients [57–58].

The diffusion of water flux during filtration is characterized by:

$$J_w = -D_w \frac{dc_w}{dx} \quad (1)$$

where  $J_w$  represents solvent flux due to the chemical potential gradient with respect to membrane,  $D_w$  represents the diffusion coefficient of the membrane solvent, and  $c_w$  solvent concentration.

However, water flux is also characterized in Eq. (2), during systematic impact due to Henry's Law, the subsequent Eq. (1) becoming:

$$J_w = \frac{D_w c_w}{R_{\text{gas}} T} \frac{d\mu_w}{dx} \approx \frac{D_w c_w}{R_{\text{gas}} T} \frac{\Delta\mu_w}{\Delta x} \quad (2)$$

where  $\mu_w$  represents chemical potential of water,  $R_{\text{gas}}$  gas constant, and  $T$  temperature.

Chemical potential represented in Eq. (2) is an immeasurable parameter, being converted to a measurable quantity as to expression Eq. (3).

$$\mu_i(T, P) = \mu_i^0(T, P^0) + R_{\text{gas}} T \ln a_i + \bar{V}_i (P - P^0) \quad (3)$$

where  $\mu_i$  represents the chemical potential component  $i$ ,  $P$  transmembrane pressure,  $P_s$  solute permeability, and

$\bar{V}_i$  partial molar volume of component  $i$ .

Subsequently, the converted equation [Eq. (3)] is substituted for Eq. (2) to obtain Eq. (4). Such a newly developed equation is practical, since  $D_w$ ,  $c_w$ , and  $\bar{V}_w$  are pressure independent.

$$J_w = \frac{D_w c_w \bar{V}_w}{R_{\text{gas}} T \Delta x} (\Delta p - \Delta \pi) \equiv A (\Delta p - \Delta \pi) \quad (4)$$

where  $\bar{V}_w$  represents partial molar water volume. The solute flux is expressed according to the concentration gradient, relying on Fick's law as expressed in Eq. (5). In such a case, the solute diffusion coefficient is assumed to be independent from salt membrane concentration ( $C_s$ ). Although the value for  $C_s$  is impossible to gauge, such a value is related to external solution concentration during linkage with distribution coefficient,  $k_s$ .

$$J_s = -D_s \frac{dc_s}{dx} \approx +D_s \frac{\Delta c_s}{\Delta x} \quad (5)$$

$$k_s = \frac{\text{grams solute/cc. membrane}}{\text{grams solute/cc. solution}} \quad (6)$$

where  $c_s$  represents local solute concentration per unit membrane volume, and  $D_s$  the diffusion coefficient of the membrane solute. As to Eq. (5), at high concentration ( $-dc_s/dx$ ) may not equal ( $+\Delta c_s/\Delta x$ ) due to the concentration profile in membranes not always being linear. Thus, by merging Eq. (5) and Eq. (6), solute flux equation becomes:

$$J_s = -D_s k_s \frac{C_p - C_R}{\Delta x} = K_2 (C_R - C_p) \quad (7)$$

where  $C_p$  represents permeate concentration,  $C_R$  rejection concentration, and  $K_2$  the coupling coefficient with pore flow description. An additional equation also related to particle transport is salt rejection, expressed as:

$$R = 1 - \frac{C_p}{C_R} = 1 - \frac{D_s k_s R_{\text{gas}} T}{D_w c_w \bar{V}_w} \cdot \frac{C_p - C_R}{C_R} \cdot \frac{1}{(\Delta P - \Delta \pi)} \quad (8)$$

Such a limitation renders the model unsuitable for real membrane application due to the microporous structures of surface layers. As mentioned previously, such a model illuminates both solute and solvent transport, relating exclusively to diffusion. Nevertheless, pore flow is significantly impacted by salt transport, as well. Further, the model inadequately portrays water or solute flux as to low water content membranes, especially for various RO membranes and organic matter [7].

##### 4.1.2. Modified solution–diffusion model (steady-state model)

A more reasonable assumption was added to the solution-diffusion model which represents steady-state

fluxes across the membrane. For organics, the total (solute and water) concentration in the membrane should be identified [59]. This implies that both the water and the solute possible to occupy within the membrane. Then water and solute fluxes written as:

$$J_w = \left( \frac{C_{tm} - C_{ms}}{C_{tm}} \right) \frac{C_{tm} D_{wm} \bar{V}_w}{R_g T \delta} (\Delta P - \Delta \pi) \tag{9}$$

$$= \left( 1 - \frac{C_{ms}}{C_{tm}} \right) A^* (\Delta P - \Delta \pi)$$

$$J_s = \frac{D_{sm}}{\delta} (C_{smf} - C_{smp}) \tag{10}$$

where  $C_{tm}$  represents the total concentration in the membrane,  $C_{ms}$  the membrane solute concentration,  $D_{wm}$  the water diffusivity in membrane,  $\bar{V}_w$  the partial molar volume of water,  $R_{gas}$  the ideal gas constant, and  $A^*$  the new permeability constant.

4.1.3. Diffusion–adsorption model (unsteady-state model)

Another modified solution-diffusion model for solutes that are able to adsorb in the membrane pores, the transport behavior can be described by a diffusion-adsorption model. This model assumed that water and solute transport occurs by uncoupled diffusion across the membrane. Solute flux can be described by Fick’s law and also the concentration of solute in the membrane can be expressed by adsorption rate [59]. The water and solute fluxes are expressed:

$$\frac{dC_c}{dt} = \frac{A_m J_w C_c - A_m J_w C_p - \frac{dQ_{tm}}{dt}}{V_f (1-r)} \tag{11}$$

$$C_p = \frac{J_s}{J_w} \tag{12}$$

where  $C_c$  represents concentrate solute concentration,  $A_m$  the membrane surface area,  $C_p$  the permeate solute concentration,  $Q_{tm}$  the total solute adsorption in membrane,  $V_f$  the feed volume, and  $r$  the permeate water recovery.

4.1.4. Solution–diffusion–imperfection model

Based on solution diffusion model limitations, the solution diffusion imperfection model was developed to augment such restrictions. Additionally, such a model is applicable for organic solutes by means of a pressure-dependent term [60]. For practical application, the pore flow term is included in the solution diffusion model. Thus, the model is effective during filtration of both surface and porous transport [7,27,61]. Total water and solute flux are represented in Eq. (13) and (14), respectively.

$$N_w = J_w + K_3 \Delta P c_w = A(\Delta P - \Delta \pi) + K_3 \Delta P c_w \tag{13}$$

$$N_s = J_s + K_3 \Delta P C_R = K_2 (C_R - C_p) + K_3 \Delta P C_R \tag{14}$$

where  $N_w$  represents water flux according to preferential sorption-capillary flow model,  $K_3$  the solute permeability coefficient,  $A$  the solvent permeability coefficient in the solution-diffusion model, and  $N_s$  total solute flux.

Referring to Eqs. (13) and (14), the permeate velocity is derived accordingly:

$$V_w = K_1 (\Delta P - \Delta \pi) + K_3 \Delta P \tag{15}$$

$$V_w C_p = K_2 (C_R - C_p) + K_3 \Delta P C_R \tag{16}$$

where  $V_w$  represents local water permeation velocity through the membrane, and  $K_1$  the water permeability coefficient. As Eqs. (15) and (16) contain the pressure drop term, useful for rejection computation, the rejection is thus calculated accordingly:

$$R = \{ C_R \Delta P (1 + K_3 / K_1) + \pi_0 (C_R + K_2 / K_1) - [ C_R^2 \Delta P^2 (1 + K_3 / K_1) + 2 C_R \Delta P \pi_0 (1 + K_3 / K_1) \cdot (C_R + K_2 / K_1) \pi_0^2 (C_R + K_2 / K_1)^2 - 4 \pi_0 \Delta P C_R^2 ]^{1/2} \} / 2 \pi_0 C_R \tag{17}$$

where  $R$  represents rejection, and  $\pi_0$  feed osmotic pressure. However, the model contains two key disadvantages: First, the model relies on parameters that are obtained exclusively by nonlinear regression, used for membrane system characterization. Second, parameters describing such systems usually characterize feed concentration and pressure functions [7]. Furthermore, the application has been shown to dilute particular organic systems ( $\Delta \pi = 0$ ), resulting in substantially lower water fluxes than predicted results [62].

4.1.5. Extended solution–diffusion model

Since the solution diffusion model is divested of possible pressure dependence as to solute chemical potential, the model is also significant for organic solutes. Thus, such a model is enriched by adding the negative solute rejection term [24,60]. Based on the modification, the solute flux is written accordingly:

$$J_s = \frac{D_{sm} K_{sm}}{\delta} (C_f - C_p) + L_{sp} \Delta P \tag{18}$$

The rejection is represented by

$$\frac{1}{R} \left[ 1 - \frac{L_{sp}}{A C_f} \left( 1 - \frac{\Delta \pi}{\Delta P} \right) \right] = 1 + \left[ \frac{B}{A (\Delta P - \Delta \pi)} \right] \tag{19}$$

where  $D_{sm}$  represents the solute diffusion coefficient in the membrane,  $K_{sm}$  the partition coefficient,  $C_f$  feed concentration,  $L_{sp}$  the phenomenological coefficient, and  $B$  the solute permeability coefficient. However, the model has not been widely applied in RO membrane models. Nevertheless, such a model fails to address substantial decreases in water flux for some dilute organic systems [62].



#### 4.1.6. Membrane surface transport model

In the model in question, solute mass transfer between membrane surfaces and cell walls are exclusively taken into account [63]. Subsequently, membranes permeate flux is clarified according to the following relation:

$$J_w = \frac{\Delta P - \Delta \pi}{\mu(R_m + R_g + R_{cp})} \quad (20)$$

where  $\mu$  represents viscosity of solution,  $R_m$  membrane resistance,  $R_{cp}$  concentration polarization resistance, and finally  $R_g$  gel layer resistance.

#### 4.1.7. Film theory diffusion model

Concentration polarization is defined as built-up intensity at membrane-liquid interfaces during filtration. Consequently, such a process, via inclusion of concentration polarization, is very crucial during transport mechanism identification. Characterized by steadiness, solute flux remains constant through films, equaling solute flux through membranes [63].

$$C_p = -D \frac{dC}{dx} + C_i F_w \quad (21)$$

where  $C_i$  represents concentration of component  $i$ .

### 4.2. Porous models

Apart from the general assumption that RO membranes are non-porous, diffusion, nevertheless, plays an important role during solvent and solute transport. However, real membranes are considered as possessing microporous surfaces. Hence, transport mechanisms not only transpire through dense layers via diffusion, but also include convection as to pores. A variety of transport models have been developed under such assumptions, demonstrated one-by-one accordingly [62].

#### 4.2.1. Preferential sorption–capillary flow model

When membrane surfaces are assumed as microporous and homogenous, membrane surface properties, dimension, and membrane pore quantity combine to play an important role during transport. Subsequently, both preferential sorption and repulsion occurred during membrane interface and solution contact. According to the model in question, coupling of surface phenomena and fluid transport via capillary pores are explained by water transport through viscous flow, solute transport via pore diffusion, and boundary layer development by means of film theories [27,62,64].

During filtration under high water pressure, water tends to be adsorbed onto pore walls, solutes being rejected and fixed on membrane surfaces. Water and salt flux are demonstrated by Eqs. (22) and (23), respectively.

$$N_w = A[\Delta P - (\pi(X_{s2}) - \pi(X_{s3}))] \quad (22)$$

$$N_s = \frac{Ck_s D_{sm}}{\delta} (X_{s2}) - (X_{s3}) \quad (23)$$

where  $N_w$  represents water flux according to the preferential sorption–capillary flow model,  $N_s$  total solute flux,  $X_{s2}$  and  $X_{s3}$  mole fractions of the solute on high and low pressure membrane sides, respectively, and  $\delta$  fouling layer thickness. The derivation of such equations is based on the solution diffusion model, in unison with the film theory, related to membrane surface and bulk solution concentrations. Furthermore, both water and solute permeability coefficients are precisely expressed in terms of operating conditions. Solute rejection is represented accordingly:

$$\frac{1}{R} = 1 + \frac{D_{sp} K_D C_T}{\delta} \frac{1}{A \{ \Delta P - [\pi(X_F) - \pi(X_P)] \}} \quad (24)$$

where  $D_{sp}$  represents solute diffusivity in membrane pores,  $X_F$  the solute mole fraction in feed water, and  $X_P$  the solute mole fraction in permeate. The model has been applied during transport analysis for numerous solutes and membranes, demonstrating that water flux drop caused by various dilute organic particles and solute rejection is not accounted for by such equations [62].

#### 4.2.2. Finely-porous model

Solute and solvent transport is directly affected by membrane surface properties. Most RO membranes consist of asymmetric structures, characterized by imperfect surface layers, such transport mechanisms representing not only diffusion but viscous flow via microporous membranes, as well [29]. Hence, the extended diffusion solution model, by the inclusion of viscous flow, represents a valuable and more accurate application for highly-porous membranes [7,27]. The total volume flux is expressed according to Poiseuille's law:

$$\epsilon u = -\frac{\epsilon r_p^2}{8\mu} \frac{dP}{dx} + \frac{\epsilon r_p^2}{8\mu} \frac{\Delta P}{\tau \Delta x} \quad (25)$$

where  $\epsilon$  represents void fraction (fractional open area),  $u$  the local center of mass velocity of pore fluid,  $r_p$  the pore radius, and, finally,  $\mu$  solution viscosity. Whereas, total solute flux is demonstrated by the following two terms: contribution due to central mass fluid motion and solute diffusion distribution:

$$N_s = c_s u + J_s \quad (26)$$

where  $J_s$  represents solute flux. Based on Eq. (26), the solute diffusion term is derived from the concentration diffusion term, as to Fick's law, coupled with the pressure diffusion term, usually negligible. Since membrane pore dimension is affected by salt permeability; the previous equation is applicable when small pore dimension is less than  $10 \text{ \AA}$ . However, if pore dimension is equal or less

than  $50 \text{ A}^0$ , the diffusion process is disturbed by solute and membrane wall friction. For this reason, the total solute flux diffusion term was modified by adding solute and membrane friction force. The modified diffusion term is expressed accordingly:

$$J_s = m_{sw} c_s \left[ - \left( \frac{\partial \mu_s}{\partial c_s} \right)_{T,p} \frac{dc_s}{dx} + F_{sm} \right] \quad (27)$$

where

$$m_{sw} = \frac{1}{f_{sw}} \quad (28)$$

$$F_{sm} = -f_{sm} (u_s - u_m^0) = -f_{sm} u_s = -f_{sm} \frac{N_s}{c_s} \quad (29)$$

where  $F_{sm}$  represents friction force between solute and membrane pores,  $f_{sm}$  the frictional coefficient between solute and membrane pores, and  $u_s$  being defined as solute flux in membrane pores divided by membrane pore concentration, and  $u_m^0$  the chemical reference pressure potential. According to the frictional model for dilute solution transport,  $(\partial \mu_s / \partial c_s)_{T,p}$  is possibly substituted with  $RT/c_s$ , also  $F_{sm}$ , as represented in the equation shown in Eq. (29), thus the modified diffusion term becoming:

$$J_s = \frac{RT}{f_{sw} c_s} \frac{dc_s}{dx} - f_{sm} \frac{N_s}{c_s} \quad (30)$$

Therefore, total solute flux [Eq. (26)] replaced by the modified diffusion term is expressed as:

$$N_s = -D_e \frac{dc_s}{dx} + \frac{c_s}{b} u \quad (31)$$

where

$$D_e = \frac{RT}{f_{sw} b} \quad (32)$$

$$b = 1 + \frac{f_{sm}}{f_{sw}} \quad (33)$$

where  $D_e$  represents the effective diffusion coefficient of micropore solutes,  $b$  the frictional force ratio acting on the mobile solute — from membrane pores to friction force — and finally,  $f_{sw}$  the frictional coefficient between solute and water. Moreover, the concentration membrane profile during applied boundary conditions, as shown in Eqs. (34) and (35), is estimated in Eq. (30),  $N_s$ ,  $u$ ,  $b$ , and  $f_{sw}$  assumed to be constant.

$$\text{at } x=0, \quad C_s = k'_s C_R \quad (34)$$

$$\text{at } x=\tau\delta, \quad C_s = k''_s C_p \quad (35)$$

Thus, the membrane concentration profile is obtained:

$$c_s = \frac{N_s b}{u} + \frac{(k'_s C_R - k''_s C_p) \exp(ux/bD_e)}{1 - \exp(u\tau\delta/bD_e)} \quad (36)$$

where  $k'_s$  and  $k''_s$  represents the partition coefficient on high and low pressure sides of membranes, respectively, and  $\tau\delta$  membrane pore length. When  $N_s = (\epsilon u) C_p$ , Eq. (36) is thus expressed as:

$$c_s = \epsilon C_p b + \frac{(k'_s C_R - k''_s C_p) \exp(ux/bD_e)}{1 - \exp(u\tau\delta/bD_e)}, \quad 0 < x < \tau\delta \quad (37)$$

Finally, the salt rejection term is derived from Eq. (33) accordingly:

$$1 - R = \frac{C_p}{C_R} = \frac{k'_s C \exp(u\tau\delta/bD_e)}{k''_s - b \epsilon \exp(u\tau\delta/bD_e)} \quad (38)$$

Based on the classical finery-porous model, which takes total membrane concentration into consideration, Josson and Boesen (1975) were able to advance a new model, relying on only a fraction of water within membrane layer and pores, as well as taking tortuosity pores into account [64]. Subsequently, the modified rejection term was concluded accordingly:

$$1 - R = \frac{C_p}{C_R} = \frac{\exp\left(\epsilon u \frac{\tau\delta}{\epsilon} / bD_e\right)}{\frac{k''_{sp}}{k'_{sp}} - \frac{b}{k'_{sp}} \left[ \exp\left(\epsilon u \frac{\tau\delta}{\epsilon} / bD_e\right) + 1 \right]} \quad (39)$$

Both Eqs. (38) and (39) are derived according to flat sheet membrane assumption, however, such terms are applicable to hollow fibers, as well. Hollow fiber walls are much thinner than flat sheet skin; therefore, such curvature is neglected, being considered identical to flat sheet membranes. In addition, Jonsson and colleagues note that such an equation supports transport mechanisms during membrane filtration, including solute membrane friction, pore dimension and distribution, and solute distribution [7,64]. In model utilization of dilute organic systems, results demonstrate that such an equation fails to address water flux decline description, compared to pure water flux. In order to correct and apply such an equation, pore dimension measurement is necessary [29].

#### 4.2.3. Surface force pore flow model

The model was augmented to include a two-dimensional extension of the finery-porous model [65]. Moreover, such a model accounts for solute concentration both in axial position and radius, in contrast to the finery-porous model which considers only axial solute concentration gradients. The model provides excellent solute separation prediction for a wide range of inorganics and organics operating under various conditions [66]. However, the model fails to adequately predict the water flux ratio for particular dilute organics, causing substantial water flux decreases. With respect to systematic accord, the pore radius is necessarily reduced to predict force and measured water flux ratio. Basic model

assumptions include water transport via membrane pores by means of viscous flow, moreover, solute transport occurring by means of diffusion and convection within membrane pores. Both solute and solvent transport is investigated by means of interaction and friction forces, as well as chemical potential barrier layer gradients [32,62]. Thus, the ratio of water flux to pure water and rejection are represented by:

$$\frac{J_w}{J_{w0}} = \frac{2 \int_0^{r_p} u r_p dr_p}{r_p^4 \Delta P} \quad (40)$$

$$R = \frac{1 - \int_0^{r_p} \left[ \frac{\exp\left(u(r_p) \delta \frac{X_{sw}}{R_g T}\right) u(r_p) r_p}{1 + \frac{b(r_p)}{\exp\left(\frac{-\phi(r_p)}{R_g T}\right)} \left[ \exp\left(u(r_p) \delta \frac{X_{sw}}{R_g T}\right) - 1 \right]} \right] dr_p}{\int_0^{r_p} u(r_p) r_p dr} \quad (41)$$

where  $X_{sw}$  is defined as  $R_g T/D_{sm}$  and  $J_{w0}$  pure water flux.

#### 4.3. Irreversible thermodynamics model

In order to understand transport mechanisms within membranes, discerning membrane structures is especially vital, transport mechanisms being mainly dependent upon such structures. However, membrane structural features are not always available so irreversible thermodynamic models have been developed to overcome such problems [27,67,68]. The models are employed on the basis of irreversibility, dividing systems into smaller entities which replicate states at equilibrium [7]. A particular strength of such an approach is multicomponent system inclusion, used to predict membrane behavior. However, such models fail to elucidate actual transfer membrane mechanisms [29]. Moreover, the models, based on inherent membrane structures and properties, are not very consequential when optimizing separation. Currently, the models likewise fall short at effective water organic flux description for various dilutes [61].

##### 4.3.1. Kedem–Katchalsky model

Kedem and Katchalsky (1958) developed a model for isothermal non-electrolyte systems in the absence of chemical reactions based on irreversible thermodynamic theories. The merits of such a model include minimal data requirement in addressing problems, as well as application ease, since parameters represent experimentally measurable quantities [68]. Furthermore, model coefficients (i.e.,  $L_p$ ,  $\sigma$ , and  $\omega$ ) rely less on degree of concentration

[69]. Conversely, the model contains one limitation — the system being exclusively closed to equilibrium states [7]. Volume ( $J_v$ ) and solute flux ( $J_s$ ) are obtained by means of linear laws and onsager reciprocal relations (ORR) as expressed below:

$$J_w = L_p(\Delta p - \sigma \Delta \pi) \quad (42)$$

$$J_s = (c_s)_m(1 - \sigma)J_w + \omega \Delta \pi \quad (43)$$

where  $L_p$  represents the Staverman reflection coefficient and  $\omega$  the solute permeability coefficient. An additional parameter important for transport models is the reflection coefficient. In such a case, the coupling of solute and solvent flux via membranes, usually employed to calculate solute rejection, is represented [50]. Specifically, solute rejection is expressed as following:

$$\frac{1}{R} = \frac{1}{\sigma} + \left( \frac{L_\pi}{L_p} - \sigma^2 \right) \left( \frac{L_p}{\sigma} \right) \pi_F \frac{1}{J_w} \quad (44)$$

where  $L_\pi$  is determined as  $\bar{V}_m$ ,  $\pi_F$  representing feed side osmotic pressure.

##### 4.3.2. Spiegler–Kedem model

Since various limitations in the Kedem–Katchalsky model exist, Spiegler and Kedem developed a model to overcome such inadequacy [7]. Included was the mention of three Kedem and Katchalsky model coefficients being less concentration-sensitive as to small volume flux and concentration gradient, conversely losing efficacy. Hence, to avoid concentration transport parameter dependence, local water ( $P_w$ ) and solute ( $P_s$ ) permeability, as well as reflection coefficients, were further defined [70]. The local phenomenological equations of solvent and solute flux, as well as the solute rejection coefficient, are represented accordingly:

$$J_w = -L_{ww} \bar{V}_w \left[ \frac{dp}{dx} - \left( 1 - \frac{L_{ws} c_w}{L_{ww} c_s} \right) \frac{d\pi}{dx} \right] \quad (45)$$

$$J_s = \left( \frac{L_{ws}^2}{c_s L_{ww}} - \frac{L_{ss}}{c_s} \right) \frac{d\pi}{dx} + \frac{L_{sw}}{L_{ww} \bar{V}_w} J_w \bar{V}_w \quad (46)$$

$$R = \frac{\sigma \left[ 1 - e^{-J_v(1-\sigma)\Delta x/p_s} \right]}{1 - \sigma e^{-J_v(1-\sigma)\Delta x/p_s}} \quad (47)$$

where  $L_{ik}$  represents phenomenological coefficients as to linear laws of irreversible thermodynamics,  $\bar{V}_w$  partial molar water volume,  $\sigma$  the reflection coefficient, and  $e$  electric ion charge. Such a model possesses meaningful RO membrane separation description and analysis due to concentration function independence. However, the model was simulated according to the “black box” model, limiting transport identification during filtration. In addition, the existence of ORR represents a further

constraint. In particular, ORR is beneficial in coefficient reduction; however, such a process is applicable only during appropriate conjugate flux and force identification, the existence of a wide linear range, and correlation with the equilibrium state [7].

#### 4.3.3. Other models based on irreversible thermodynamics

An additional RO transport model, developed on irreversible thermodynamics though reducing ORR, is acknowledged [7]. Previous studies have revealed varying degrees of success in the use of dimensional analysis to correlate experimental RO membrane data. Mason and Lonsdale (1990) presented the statistical-mechanical membrane transport theory, pointing out that most RO membrane transport models are possibly derived from statistical-mechanical theories [71]. Furthermore, extended Stefan-Maxwell equations were revealed to illustrate total aqueous-organic solution flux (solute plus solvent) via membranes; the model indicating water flux reduction was partly due to frictional organic effects [61]. The model includes the form:

$$N_T = \frac{A \{ \Delta P - [\pi(X_F) - \pi(X_p)] \}}{1 + W_s X_p} \quad (48)$$

where  $N_T$  represent total flux,  $X_F$  the solute mole fraction in feed water,  $X_p$  the solute mole fraction in permeate, and finally  $W_s X_p$  the solute membrane friction term. Subsequently, an additional development is exposed by using the adsorption resistance term ( $R_{Ads}$ ) to illuminate water flux decline in aqueous-organic systems. The model is rooted in the assumption that organics adsorbed on membranes influence high resistance of water flow through membranes. Moreover, such an equation has also been applied extensively in illuminating ultrafiltration membranes [72–74]. Water flux is represented as:

$$J_w = \frac{\Delta P - \Delta \pi}{R_m + R_{Ads}} \quad (49)$$

An alternative model is the frictional model, the equations within the model possessing notably uncomplicated physical interpretation. Components are assumed to move in a quasi-steady state in which driving force is balanced by frictional force gradient [7]. Frictional forces are assumed to be proportional to velocity differences between components and frictional drag origins [8,75–81]. The total force acting on water and salt are expressed accordingly:

$$F_w = (c_s / c_w) f_{sw} (u_w - u_s) + f_{wm} (u_w - u_m) \quad (50)$$

$$F_s = f_{sw} (u_s - u_w) + f_{sm} (u_s - u_m) \quad (51)$$

where  $F_s$  represents total force acting on salt and  $F_w$  total force acting on water. Thus, solvent and solute flux are expressed according to Eqs. (52) and (53), respectively.

$$J_w = \frac{(f_{sm} + f_{sw}) c_w^2}{d} F_w + \frac{f_{sw} c_w c_s}{d} F_s \quad (52)$$

$$J_s = \frac{f_{sw} c_w c_s}{d} F_w + \frac{(f_{wm} c_w + f_{sw} c_s) c_s}{d} F_s \quad (53)$$

Recently, modified concentration polarization model is developed since concentration polarization in the cross-flow RO process plays an important role inducing fouling. The development of this model starts from the principle of irreversible thermodynamics including theory of concentration polarization. As well as, the additional osmotic pressure arising from concentration polarization layer has been considered [82]. Thus, permeate flux in cross-flow RO process can be written as:

$$\Delta P = R_m v(x) + \frac{n \phi R_{gs} TR c_0}{D^2 \gamma} v(x)^2 \int_0^x v(x') dx' \quad (54)$$

where the additional osmotic pressure due to concentration polarization is determined as:

$$\Delta \pi_a = \frac{n \phi R_{gs} TR c_0}{D^2 \gamma} v(x)^2 \int_0^x v(x') dx' \quad (55)$$

where  $v(x)$  represents permeate flux at  $x$ ,  $n$  the number of ions in electrolyte,  $c_0$  feed solute concentration,  $D$  the solute diffusion coefficient,  $\gamma$  the shear rate,  $x'$  the dummy integration variable, and  $\Delta \pi_a$  the additional osmotic pressure.

## 5. Conclusions

To date, RO transport models and fouling mechanisms have been deliberated by numerous researchers over many decades. Nevertheless, fouling mechanisms, especially relating to NOM, have not been adequately elucidated. In particular, NOM fouling mechanisms, e.g., complex interactions between foulant-foulant and foulant-membrane surfaces due to various influential factors, simultaneously governing processes such as solution chemistry (e.g., pH, ionic strength and water hardness) [46,47,49–53]; membrane characteristics (e.g., hydrophobicity; surface/pore charge; (MWCO and morphology) [18,38,45–47,49,50]; operational conditions; inorganic presence and NOM characteristics (e.g., concentration, humic and non-humic fractions, charge, MW distribution) assist in explaining such lack of clarification [35]; physical condition such as pressure [49]. Additionally, the contribution of NOM fouling greatly depends on feed water properties, NOM characteristics, as well as manners of pretreatment. Thus, RO transport modeling during seawater desalination, especially NOM fouling development, has become a major challenge towards more effective fouling control and widespread RO application. Currently, RO transport models are categorized as to membrane surface structure composition according



to the following 3 types: diffusion-based, pore, and irreversible thermodynamic models [7]. In order to develop NOM fouling models for SWRO application, a number of studies have revealed challenges in solute system application, especially involving dilute organics. In particular, such models fail to adequately illuminate water flux decline [7,62]. Consequently, simplification is possibly accomplished by particular term introduction, impacting NOM fouling as to aforementioned models. However, several researchers have observed that such methods fail to adequately predict NOM fouling. Major difficulties with NOM fouling models are symbolized by lack of exact characterization (e.g., functional NOM group) and reliable linkage among feed water compositions, fouling rates, foulant transport and NOM characteristics. In addition, fouling model development depends on experimental verification methods and fouling potential, as well as existing operating conditions. Accordingly, specific NOM fouling models for SWRO application have not been fully developed to date. Therefore, to achieve high NOM fouling prediction accuracy as to SWRO application a holistic understanding of NOM fouling mechanisms, coupled with integrated experimentation, is required for NOM fouling model set-up.

## 6. Future direction of NOM fouling model

Predictive NOM fouling models, modified according to existing models, specifically require coefficient and modulating factor determination. In order to understand NOM fouling mechanisms, experimental data, i.e., intermolecular adhesion and hydrodynamic shear force, permeation drag, as well as membrane autopsy coupled with image analysis, is required. Correlation among factors effecting NOM fouling requires increased consideration due to the simultaneous and factor-varying nature of the process. Moreover, cross flow membrane filtration coupled with image analysis (i.e. AFM, TEM, CLSM and SEM), aiding in enhanced understanding of NOM fouling mechanisms and mass transport phenomena, is ideally applied to obtain essential model set-up information. Finally, NOM fouling models utilized for SWRO application are ideally modified by adding specific coefficients obtained from existing classic RO transport models. An additional aspect necessary in such deliberation is seawater NOM extraction. To date, all experiments designed for better understanding of fouling seawater mechanisms have been conducted by using extracted freshwater or synthetic NOM. Hence, high precision and accuracy is likely achieved via seawater NOM experimentation. Precisely, NOM characteristics and composition emanating from a variety of unique sources help to explain such likely results.

In brief, a clear understanding of NOM fouling mechanisms, as well as solutions preventing fouling problems during SWRO, are necessary for long-term fouling pre-

vention. Moreover, in order to better understand NOM fouling mechanisms as a result of increasing concerns over the role and importance of humic substances as to various aspects of water chemistry, the need for a more concerted effort and approach has transpired. In the case in question, RO transport modeling, likely explaining transport particle phenomena including NOM, is essential in overcoming such problems.

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## Symbols

$A$	—	Solvent permeability coefficient in solution-diffusion model
$A^*$	—	A new permeability constant
$A_m$	—	Membrane surface area
$a_i$	—	Chemical activity of component $i$
$B$	—	Solute permeability coefficient
$b$	—	Ratio of the frictional force acting on the solute moving in a membrane pore to the friction force
$C$	—	Concentration from the bulk to the membrane interfacial
$C_b$	—	Bulk concentration
$C_c$	—	Concentrate solute concentration
$C_F$	—	Feed concentration
$C_g$	—	Gel layer concentration
$C_i$	—	Concentration of component $i$
$C_m$	—	Concentration at membrane surface
$(C_m)_{avg}$	—	Logarithmic mean solute concentration in membrane
$C_{ms}$	—	Membrane solute concentration
$C_p$	—	Permeate concentration
$C_R$	—	Rejection concentration
$C_{smf}$	—	Solute membrane concentration which related to feed concentration
$C_{smp}$	—	Solute membrane concentration which related to permeate concentration
$c_w$	—	Solvent concentration
$c_s$	—	Local solute concentration per unit membrane volume
$c_0$	—	Feed solute concentration
$D$	—	Solute diffusion coefficient
$D_e$	—	The effective diffusion coefficient of the solute in a micropore
$D_s$	—	Diffusion coefficient of the solute in the membrane
$D_{sm}$	—	Solute diffusion coefficient in the membrane
$D_{sp}$	—	Diffusivity of the solute of the solute in the membrane pore

$D_w$	— Diffusion coefficient of the solvent in the membrane	$R$	— Rejection
$D_{wm}$	— Water diffusivity in membrane	$R_{Ads}$	— Solute adsorption resistance
$d$	— $d = f_{sm} + f_{wm}c_w + f_{sm}f_{sw}c_s + f_{sw}f_{wm}c_w$	$R_{cp}$	— Concentration polarization resistance
$e$	— Electric charge of the ion	$R_s$	— Gel layer resistance
$F_s$	— Total force acting on salt	$R^{gas}$	— Gas constant
$F_w$	— Total force acting on water	$R_{in}$	— Internal pore fouling resistance
$F_{sm}$	— Friction force between solute and membrane pore	$R_m$	— Membrane resistance
$f_{ik}$	— Frictional coefficient	$T$	— Temperature
$f_{im}$	— Frictional coefficient	$r$	— Permeate water recovery
$f_{sm}$	— Frictional coefficient between solute and membrane pore	$r_p$	— Pore radius
$f_{sw}$	— Frictional coefficient between solute and water	$u$	— Local center-of-mass velocity of pore fluid
$J_i$	— Fluxes	$u_s$	— Defined as solute flux in membrane pore divided by concentration in membrane pore
$J_s$	— Solute flux	$u_m^0$	— Chemical potential at the reference pressure
$J_v$	— Volume flux; the sum of the diffusive solute and solvent fluxes (due to the $J_w$ water flux gradient of chemical potential)	$\bar{V}_i$	— Partial molar volume of component $i$
$J_w$	— Flux of solvent due to the gradient of chemical potential with respect to membrane	$\bar{V}_w$	— Partial molar volume of water
$J_{w0}$	— Pure water flux	$V_F$	— Feed volume
$K_1$	— Water permeability coefficient	$V_w$	— Local water permeation velocity through the membrane
$K_2$	— Coupling coefficient describing pore flow	$v(x)$	— Permeate flux at point $x$
$K_3$	— Solute permeability coefficient	$v_i$	— Average velocity
$K_D$	— Distribution coefficient of the solute from the feed into the pore of membrane	$W_s X_p$	— Solute membrane friction term
$K_{sm}$	— Partition coefficient defined as $K_{sm} = C_{sm}/C_F = C_{sm}/C_p$	$X_F$	— Solute mole fraction in feed water
$k$	— Boltzman constant	$X_i$	— Forces
$k_s$	— Partition coefficient of the solute in the membrane with respect to the total membrane volume	$X_p$	— Solute mole fraction in permeate
$k'_s, k''_s$	— Partition coefficient in the high and low pressure sides of membrane, respectively	$X_{s2}$	— Mole fraction of the solute in the high pressure sides of the membrane
$k'_{sp}, k''_{sp}$	— Partition coefficient with respect to the pore volume in the high and low pressure sides of the membrane, respectively	$X_{s3}$	— Mole fraction of the solute in the low pressure sides of the membrane
$L_{ik}$	— Phenomenological coefficients in the linear laws of irreversible thermodynamics	$X_{sw}$	— Defined as $R_g T/D_{sm}$
$L_p$	— Staverman reflection coefficient	<i>Greek</i>	
$L_\pi$	— Determined from $\omega = (L_\pi/L_p - \sigma^2)$	$\delta$	— Fouling layer thickness
$m_{sw}$	— Mobility of solute in membrane	$\phi$	— Local dissipation function
$N_i$	— Flux (diffusion and convection) of component $i$ with respect to the fixed coordinate (membrane)	$\mu$	— Viscosity of solution
$N_s$	— Total solute flux	$\mu_w$	— Chemical potential of water
$N_T$	— Total flux (solvent and solute) with respect to the fixed coordinate (membrane)	$\mu_i$	— Chemical potential component $i$
$N_w$	— Water flux according to preferential sorption-capillary flow model	$\mu_i^0$	— Chemical potential at reference pressure
$n$	— Number of ions in electrolyte	$\mu_s$	— Chemical potential of solute
$P$	— Transmembrane pressure	$\pi$	— Osmotic pressure
$P_s$	— Solute permeability	$\pi_a$	— Additional osmotic pressure
$P^0$	— Reference pressure	$\pi_0$	— Feed osmotic pressure
$Q_{tm}$	— Total solute adsorption in membrane	$\pi_F$	— Osmotic pressure on the feed side
		$\pi_R$	— Osmotic pressure on the reject side
		$\sigma$	— Reflection coefficient
		$\tau$	— Tortuosity of the membrane
		$\tau\delta$	— Length of membrane pore
		$\omega$	— Coefficient of solute permeability in Kedem-Katchalsky model
		$\epsilon$	— Void fraction (fractional open area) of the membrane
		<i>Subscripts</i>	
		$b$	— Bulk solution
		$m$	— Membrane

- p* — Pore  
*s* — Solute (salt)  
*w* — Solvent (water)

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